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CONTROL AUTOMÁTICO	Dr. Emmanuel Nuño Ortega	Emmanuel Nuño SCOPUS Autor Romeo Ortega	Achieving Consensus of Euler-Lagrange Agents With Interconnecting Delays and Without Velocity Measurements via Passivity-Based Control	2018	ISSN: 10636536
		Emmanuel Nuño SCOPUS Autor Marco Arteaga-Pérez SCOPUS Autor Gerardo Espinosa-Pérez	Control of bilateral teleoperators with time delays using only position measurements	2018	ISSN: 10498923
		Rodrigo Munguía SCOPUS Autor Carlos López-Franco SCOPUS Autor Emmanuel Nuño SCOPUS Autor Adriana López-Franco	Method for SLAM Based on Omnidirectional Vision: A Delayed-EKF Approach	2017	ISSN: 1687725X
		Emmanuel Nuño SCOPUS Autor Carlos I. Aldana SCOPUS Autor Rodrigo Munguía SCOPUS Autor Remberto Machuca	Cartesian space consensus of heterogeneous and uncertain Euler-Lagrange systems using artificial neural networks	2017	ISSN: 15986446
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